6.01 Introduction to EECS via Robotics

Lecture 3: Analyzing System Behavior

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As you come in...
- Grab one handout (on the table by the entrance)
Describe a **system** (physical, mathematical, or computational) by the way it transforms an input signal into an output signal.
The Signals and Systems Abstraction

Describe a **system** (physical, mathematical, or computational) by the way it transforms an input signal into an output signal.

![System Diagram]

Focus on **Linear, Time-Invariant** (LTI) Systems.
Signals and Systems: Representations

Last week, 3 main representations:

- Difference Equation
- Block Diagram
- Operator Equation

Today, 2 new representations:

- System Functional
- Poles
Signals and Systems: Representations

Last week, 3 main representations:

- Difference Equation
- Block Diagram
- Operator Equation

Today, 2 new representations:

- System Functional
- Poles
Example: wallFinder

Consider the wallFinder from design lab 1 and 2:

Think about this system as having 2 parts:
Example: `wallFinder`

Controller (brain): sets commanded velocity $\propto$ error:

$$\begin{align*}
   v_c[n] &= k_e d_i[n] = k (d_i[n] - d_s[n])
\end{align*}$$

Plant (robot locomotion): given $v_c[n]$, derives new position:

$$\begin{align*}
   v_a[n] &= v_c[n] - 1 \\
   p[n] &= p[n] - 1 + T d_s[n] \\
   d_s[n] &= -p[n]
\end{align*}$$
Example: `wallFinder`

Controller (brain): sets commanded velocity ∝ error:

\[ v_c[n] = ke[n] = k(d_i[n] - d_s[n]) \]
Example: wallFinder

Controller (brain): sets commanded velocity $\propto$ error:

$$v_c[n] = ke[n] = k(d_i[n] - d_s[n])$$

Plant (robot locomotion): given $v_c[n]$, derives new position:

$$v_a[n] = v_c[n - 1]$$

$$p[n] = p[n - 1] + Tv[n - 1]$$

$$d_s[n] = -p[n]$$
Check Yourself!

Solving difference equations:

\[ v_c[n] = ke[n] = k(d_i[n] - d_s[n]) \]
\[ v_a[n] = v_c[n - 1] \]
\[ p[n] = p[n - 1] + T v_a[n - 1] \]
\[ d_s[n] = -p[n] \]

How many equations? How many unknowns?

1. 4 equations; 4 unknowns
2. 4 equations; 5 unknowns
3. 5 equations; 5 unknowns
4. 4 equations; 8 unknowns
5. none of the above

*Hint:* \( T \) and \( k \) are fixed (constant) parameters and the input is known.
Check Yourself!

Solving difference equations:

\[ v_c[n] = k e[n] = k(d_i[n] - d_s[n]) \]
\[ v_a[n] = v_c[n - 1] \]
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Hint: \( T \) and \( k \) are fixed (constant) parameters and the input is known.
Check Yourself!

Solving operator equations:

\[ V_c = k(D_i - D_s) \]
\[ V_a = R V_c \]
\[ P = R P + T R V_a \]
\[ D_s = -P \]

How many equations? How many unknowns?

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Solving operator equations:

\[ V_c = k(D_i - D_s) \]

\[ V_a = R V_c \]

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How many equations? How many unknowns?

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5. none of the above

*Hint*: \( T \) and \( k \) are fixed (constant) parameters and the input is known.
System Functional

We can express the relation between the (known) input and the (unknown) output using the system functional $\mathcal{H}$.

$$X \xrightarrow{\mathcal{H}} Y$$

The system functional $\mathcal{H}$ is an operator.

Applying $\mathcal{H}$ to $X$ yields $Y$.

$$Y = \mathcal{H}X$$

It is also convenient to think of $\mathcal{H}$ as a ratio:

$$\mathcal{H} = \frac{Y}{X}$$
System Functional: Primitives

Gain:

\[ \frac{Y}{X} = k \]

Delay:

\[ \frac{Y}{X} = \mathcal{R} \]
Consider two systems (with system functionals $\mathcal{H}_1$ and $\mathcal{H}_2$) connected in \textit{feedforward add} configuration:

$$
\begin{align*}
\mathcal{H}_1 & \quad X \\
+ & \\
\mathcal{H}_2 & \quad Y \\
\end{align*}
$$

What is the system functional $\frac{Y}{X}$ of this composite system?
Consider two systems (with system functionals $H_1$ and $H_2$) connected in feedforward add configuration:

What is the system functional $\frac{Y}{X}$ of this composite system?
System Functional: Feedforward Add

Consider two systems (with system functionals $H_1$ and $H_2$) connected in feedforward add configuration:

What is the system functional $\frac{Y}{X}$ of this composite system?

$$A = H_1X \quad B = H_2X$$

$$Y = A + B = H_1X + H_2X = (H_1 + H_2)X$$
Consider two systems (with system functionals $\mathcal{H}_1$ and $\mathcal{H}_2$) connected in feedforward add configuration:

$$\mathcal{H}_1 \xrightarrow{\mathcal{H}_2} A \xrightarrow{+} X \quad Y \xleftarrow{B}$$

What is the system functional $\frac{Y}{X}$ of this composite system?

$$A = \mathcal{H}_1 X \quad B = \mathcal{H}_2 X$$

$$Y = A + B = \mathcal{H}_1 X + \mathcal{H}_2 X = (\mathcal{H}_1 + \mathcal{H}_2)X$$

$$\mathcal{H} = \frac{Y}{X} = \mathcal{H}_1 + \mathcal{H}_2$$
Consider two systems (with system functionals $\mathcal{H}_1$ and $\mathcal{H}_2$) connected in cascade configuration:

$$X \rightarrow \mathcal{H}_1 \rightarrow \mathcal{H}_2 \rightarrow Y$$

What is the system functional $\frac{Y}{X}$ of this composite system?
System Functional: Cascade

Consider two systems (with system functionals $\mathcal{H}_1$ and $\mathcal{H}_2$) connected in *cascade* configuration:

\[ X \xrightarrow{A} Y \]

What is the system functional $\frac{Y}{X}$ of this composite system?
Consider two systems (with system functionals $H_1$ and $H_2$) connected in cascade configuration:

$$X \xrightarrow{H_1} A \xrightarrow{H_2} Y$$

What is the system functional $\frac{Y}{X}$ of this composite system?

$$A = H_1 X$$

$$Y = H_2 A = H_2 H_1 X$$
Consider two systems (with system functionals $\mathcal{H}_1$ and $\mathcal{H}_2$) connected in cascade configuration:

$$X \xrightarrow{A} \mathcal{H}_1 \xrightarrow{} \mathcal{H}_2 \xrightarrow{} Y$$

What is the system functional $\frac{Y}{X}$ of this composite system?

$$A = \mathcal{H}_1 X$$

$$Y = \mathcal{H}_2 A = \mathcal{H}_2 \mathcal{H}_1 X$$

$$\mathcal{H} = \frac{Y}{X} = \mathcal{H}_2 \mathcal{H}_1$$
Consider two systems (with system functionals $\mathcal{H}_1$ and $\mathcal{H}_2$) connected in feedback add configuration:

$$X \rightarrow + \rightarrow \mathcal{H}_1 \rightarrow Y$$

$$\mathcal{H}_2 \leftarrow$$

What is the system functional $\frac{Y}{X}$ of this composite system?
Consider two systems (with system functionals $\mathcal{H}_1$ and $\mathcal{H}_2$) connected in feedback add configuration:

![Diagram of feedback add configuration]

What is the system functional $\frac{Y}{X}$ of this composite system?
Consider two systems (with system functionals $\mathcal{H}_1$ and $\mathcal{H}_2$) connected in feedback add configuration:

$$A = \mathcal{H}_2 Y \quad B = X + A$$

$$Y = \mathcal{H}_1 B = \mathcal{H}_1 (X + A) = \mathcal{H}_1 (X + \mathcal{H}_2 Y)$$
Consider two systems (with system functionals $H_1$ and $H_2$) connected in feedback add configuration:

$$X \rightarrow + \quad B \quad \rightarrow \quad H_1 \quad \rightarrow \quad Y$$

$$A \quad \rightarrow \quad H_2 \quad \rightarrow \quad A$$

What is the system functional $\frac{Y}{X}$ of this composite system?

$$A = H_2 Y \quad \quad B = X + A$$

$$Y = H_1 B = H_1 (X + A) = H_1 (X + H_2 Y)$$

$$H = \frac{Y}{X} = \frac{H_1}{1 - H_1 H_2}$$
Feedback

Feedback (as we saw in lab last week) is pervasive in natural and artificial systems.

Driving, trying to keep the car in the center of the road:

![Diagram showing feedback control in driving](image)
Control Systems: Feedback is useful for regulating a system’s behavior

- Desired temperature
- Thermostat
- Heating system
- Actual temperature
Example: Glucose Regulation

- Food enters the digestive system, which breaks down food into glucose.
- Glucose enters the circulatory system.
- The pancreas (β cells) releases insulin in response to high glucose levels.
- Insulin reduces glucose concentration in the body.
- Glucose concentration in the body also affects insulin release from the pancreas.

Diagram:

- Food → Glucose system → Circulatory system → Cells & tissues
- Pancreas (β cells) releases insulin in response to high glucose levels.
- Insulin concentration in the body also affects glucose concentration.

Equation:

\[ \text{food} \rightarrow \text{glucose system} \rightarrow \text{circulatory system} \rightarrow \text{cells & tissues} \]

\[ \text{pancreas (β cells)} \rightarrow \text{insulin} \rightarrow \text{glucose concentration} \]
Example: Glucose Regulation
Example: Glucose Regulation
Consider a small feedback system:

\[ y[n] = x[n] + p_0 y[n-1] \]

Find \( y[n] \) given \( x[n] = \delta[n] \):

\[
\begin{align*}
  y[0] &= x[0] + p_0 y[-1] = 1 + 0 = 1 \\
  y[1] &= x[1] + p_0 y[0] = 0 + p_0 = p_0 \\
  &\vdots
\end{align*}
\]
Feedback

Consider a small feedback system:

\[ x[n] \rightarrow + \rightarrow y[n] \]

\[ p_0 \rightarrow \mathcal{R} \]

Find \( y[n] \) given \( x[n] = \delta[n] \):

\[ y[n] = x[n] + p_0 y[n - 1] \]

\[ x[n] = \delta[n] \]

\[ y[n] \]

\[ n \]
Consider a small feedback system:

\[ x[n] \rightarrow + \rightarrow y[n] \]

Find \( y[n] \) given \( x[n] = \delta[n] \):

\[ y[n] = x[n] + p_0 y[n-1] \]

\[ y[0] = x[0] + p_0 y[-1] = 1 + 0 = 1 \]
Feedback

Consider a small feedback system:

\[ x[n] \rightarrow + \rightarrow y[n] \]

\[ y[n] = x[n] + p_0 y[n-1] \]

Find \( y[n] \) given \( x[n] = \delta[n] \):

\[ y[0] = x[0] + p_0 y[-1] = 1 + 0 = 1 \]
\[ y[1] = x[1] + p_0 y[0] = 0 + p_0 = p_0 \]
Feedback

Consider a small feedback system:

\[ x[n] \rightarrow \oplus \rightarrow y[n] \]

\[ p_0 \rightarrow \mathbb{R} \quad \text{feedback loop} \]

Find \( y[n] \) given \( x[n] = \delta[n] \):

\[
\begin{align*}
  y[n] &= x[n] + p_0 y[n - 1] \\
  y[0] &= x[0] + p_0 y[-1] = 1 + 0 = 1 \\
  y[1] &= x[1] + p_0 y[0] = 0 + p_0 = p_0 \\
\end{align*}
\]

\( x[n] = \delta[n] \)

\( y[n] \) for \( n = 0, 1, 2, 3, 4 \):
Consider a small feedback system:

\[ x[n] \rightarrow + \rightarrow y[n] \]

\[ \begin{align*}
  x[n] & = \delta[n] \\
  y[n] & = x[n] + p_0 y[n-1] \\
  y[0] & = x[0] + p_0 y[-1] = 1 + 0 = 1 \\
  y[1] & = x[1] + p_0 y[0] = 0 + p_0 = p_0 \\
  \vdots 
\end{align*} \]
Consider a small feedback system:

\[ x[n] \rightarrow + \rightarrow y[n] \]

\[ p_0 \leftarrow \mathcal{R} \leftarrow \]

Find \( y[n] \) given \( x[n] = \delta[n] \):

\[ y[n] = x[n] + p_0 y[n-1] \]

\[ y[0] = x[0] + p_0 y[-1] = 1 + 0 = 1 \]
\[ y[1] = x[1] + p_0 y[0] = 0 + p_0 = p_0 \]
\[ y[2] = x[2] + p_0 y[1] = 0 + p_0^2 = p_0^2 \]

\( x[n] = \delta[n] \)

\[ \cdots \]

\( y[n] \)

\[ n \]

\[ n \]

\[ -1 \quad 0 \quad 1 \quad 2 \quad 3 \quad 4 \]

\[ \cdots \]

\[ -1 \quad 0 \quad 1 \quad 2 \quad 3 \quad 4 \]

\[ \cdots \]
Alternatively, we can think about *signals* instead of *samples*.

\[ Y = X + p_0 \mathcal{R} Y \]

\[ (1 - p_0 \mathcal{R})Y = X \]
Feedback

Alternatively, we can think about *signals* instead of *samples*. 

\[
x[n] \rightarrow + \rightarrow y[n] \\
\]

\[
Y = X + p_0 \mathcal{R} Y \\
(1 - p_0 \mathcal{R})Y = X \\
\frac{Y}{X} = \frac{1}{1 - p_0 \mathcal{R}}
\]
$$\frac{Y}{X} = \frac{1}{1 - p_0 R}$$
\[ \frac{Y}{X} = \frac{1}{1 - p_0 R} \]

We can show that this is right algebraically:
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\[
\frac{Y}{X} = \frac{1}{1 - p_0 R}
\]

\[
\begin{array}{c|c}
1 - p_0 R & 1 + p_0 R + p_0^2 R^2 + p_0^3 R^3 + \cdots \\
1 & 1 - p_0 R \\
1 - p_0 R & p_0 R \\
p_0 R & -p_0^2 R^2 \\
p_0^2 R^2 & p_0^3 R^3 \\
p_0^3 R^3 & -p_0^4 R^4 \\
p_0^3 R^3 & -p_0^4 R^4 \\
\cdots
\end{array}
\]
\[ \frac{Y}{X} = \frac{1}{1 - p_0 \mathcal{R}} \]

We can show that this is right algebraically:

\[
\begin{array}{c}
1 \quad + p_0 \mathcal{R} \quad + p_0^2 \mathcal{R}^2 \quad + p_0^3 \mathcal{R}^3 \quad + \cdots \\
\hline
1 - p_0 \mathcal{R} \\
1 - p_0 \mathcal{R} \\
1 - p_0 \mathcal{R} \\
\hline
p_0 \mathcal{R} \\
p_0 \mathcal{R} \\
p_0 \mathcal{R} \\
p_0 \mathcal{R} \\
p_0 \mathcal{R} \\
p_0 \mathcal{R} \\
p_0 \mathcal{R} \\
p_0 \mathcal{R} \\
\hline
p_0^3 \mathcal{R}^3 \\
p_0^3 \mathcal{R}^3 \\
p_0^3 \mathcal{R}^3 \\
p_0^3 \mathcal{R}^3 \\
p_0^3 \mathcal{R}^3 \\
p_0^3 \mathcal{R}^3 \\
p_0^3 \mathcal{R}^3 \\
p_0^3 \mathcal{R}^3 \\
p_0^3 \mathcal{R}^3 \\
p_0^3 \mathcal{R}^3 \\
p_0^3 \mathcal{R}^3 \\
\hline
p_0^4 \mathcal{R}^4 \\
p_0^4 \mathcal{R}^4 \\
p_0^4 \mathcal{R}^4 \\
p_0^4 \mathcal{R}^4 \\
p_0^4 \mathcal{R}^4 \\
p_0^4 \mathcal{R}^4 \\
p_0^4 \mathcal{R}^4 \\
p_0^4 \mathcal{R}^4 \\
p_0^4 \mathcal{R}^4 \\
p_0^4 \mathcal{R}^4 \\
p_0^4 \mathcal{R}^4 \\
\hline
\cdots
\end{array}
\]

Therefore, \( \frac{1}{1 - p_0 \mathcal{R}} = 1 + p_0 \mathcal{R} + p_0^2 \mathcal{R}^2 + p_0^3 \mathcal{R}^3 + p_0^4 \mathcal{R}^4 + \cdots \)
Feedback: Cyclic Signal Flow Paths

We can also see this graphically:

\[
\frac{Y}{X} = \frac{1}{1 - p_0 R}
\]
Feedback: Cyclic Signal Flow Paths

We can also see this graphically:

\[
\frac{Y}{X} = \frac{1}{1 - p_o R} = 1
\]
Feedback: Cyclic Signal Flow Paths

We can also see this graphically:

\[
\frac{Y}{X} = \frac{1}{1 - p_0 R} = 1 + p_0 R
\]
Feedback: Cyclic Signal Flow Paths

We can also see this graphically:

\[
\frac{Y}{X} = \frac{1}{1 - p_0 R} = 1 + p_0 R + p_0^2 R^2
\]
Feedback: Cyclic Signal Flow Paths

We can also see this graphically:

\[
\frac{Y}{X} = \frac{1}{1 - p_0 R} = 1 + p_0 R + p_0^2 R^2 + p_0^3 R^3
\]
We can also see this graphically:

\[
\frac{Y}{X} = \frac{1}{1 - p_0 R} = 1 + p_0 R + p_0^2 R^2 + p_0^3 R^3 + p_0^4 R^4
\]
We can also see this graphically:

\[
\frac{Y}{X} = \frac{1}{1 - p_o \mathcal{R}} = 1 + p_0 \mathcal{R} + p_0^2 \mathcal{R}^2 + p_0^3 \mathcal{R}^3 + p_0^4 \mathcal{R}^4 + \ldots
\]
Feedback: Cyclic Signal Flow Paths

We can also see this graphically:

\[
\frac{Y}{X} = \frac{1}{1 - p_0 R} = 1 + p_0 R + p_0^2 R^2 + p_0^3 R^3 + p_0^4 R^4 + \ldots
\]

Cyclic flow paths: \textit{persistent} response to \textit{transient} input.
Geometric Growth

If traversing the cycle decreases or increases the magnitude of the signal, then the output will decay or grow.

Geometric Sequences:

\[ y[n] = (1.2)^n \] and \[ y[n] = (0.5)^n \] for \( n \geq 0 \).

These responses can be characterized by a single number (the pole), which is the base of the geometric sequence.
Geometric Growth

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Geometric Growth

If traversing the cycle decreases or increases the magnitude of the signal, then the output will decay or grow.

**Geometric Sequences:** $y[n] = (1.2)^n$ and $(0.5)^n$ for $n \geq 0$.
These responses can be characterized by a single number (the pole), which is the base of the geometric sequence.
\( p_0 = 0.9 \)

\[ y[0] = (0.90)^0 \approx 1.000000 \]
\( p_0 = 0.9 \)

\[ y[1] = (0.90)^1 \approx 0.900000 \]
\( p_0 = 0.9 \)

\[ y[2] = (0.90)^2 \approx 0.810000 \]
\[ p_0 = 0.9 \]

\[ y[3] = (0.90)^3 \approx 0.729000 \]
\( p_0 = 0.9 \)

\[ y[4] = (0.90)^4 \approx 0.656100 \]
$p_0 = 0.9$

\[ y[5] = (0.90)^5 \approx 0.590490 \]
$p_0 = 0.9$

$y[6] = (0.90)^6 \approx 0.531441$
\[ p_0 = 0.9 \]

\[ y[7] = (0.90)^7 \approx 0.478297 \]
\[ p_0 = 0.9 \]

\[ y[8] = (0.90)^8 \approx 0.430467 \]
\[ p_0 = 0.9 \]

\[ y[9] = (0.90)^9 \approx 0.387420 \]
\( p_0 = 0.9 \)

\[ y[10] = (0.90)^{10} \approx 0.348678 \]
$p_0 = 0.9$

$y[11] = (0.90)^{11} \approx 0.313811$
\[ p_0 = 0.9 \]

\[ y[12] = (0.90)^{12} \approx 0.282430 \]
\[ p_0 = 0.9 \]

\[ y[13] = (0.90)^{13} \approx 0.254187 \]
$p_0 = 0.9$

$y[14] = (0.90)^{14} \approx 0.228768$
\( p_0 = 0.9 \)

\[ y[15] = (0.90)^{15} \approx 0.205891 \]
$p_0 = 0.9$

$y[16] = (0.90)^{16} \approx 0.185302$
\[ p_0 = 0.9 \]

\[ y[17] = (0.90)^{17} \approx 0.166772 \]
\[ p_0 = 0.9 \]

\[ y[18] = (0.90)^{18} \approx 0.150095 \]
\[ p_0 = 0.9 \]

\[ y[19] = (0.90)^{19} \approx 0.135085 \]
\[ p_0 = 1.1 \]

\[ y[0] = (1.05)^0 \approx 1.000000 \]
$p_0 = 1.1$

\[ y[1] = (1.05)^1 \approx 1.050000 \]
$$p_0 = 1.1$$

$$y[2] = (1.05)^2 \approx 1.102500$$
$p_0 = 1.1$

$y[3] = (1.05)^3 \approx 1.157625$
$p_0 = 1.1$

$y[4] = (1.05)^4 \approx 1.215506$
\( p_0 = 1.1 \)

\[ y[5] = (1.05)^5 \approx 1.276282 \]
\[ p_0 = 1.1 \]

\[ y[6] = (1.05)^6 \approx 1.340096 \]
\( p_0 = 1.1 \)

\[ y[7] = (1.05)^7 \approx 1.407100 \]
$p_0 = 1.1$

$y[8] = (1.05)^8 \approx 1.477455$
$p_0 = 1.1$

$y[9] = (1.05)^9 \approx 1.551328$
$p_0 = 1.1$

\[ y[10] = (1.05)^{10} \approx 1.628895 \]
\[ p_0 = 1.1 \]

\[ y[11] = (1.05)^{11} \approx 1.710339 \]
$p_0 = 1.1$

$y[12] = (1.05)^{12} \approx 1.795856$
\( p_0 = 1.1 \)

\[ y[13] = (1.05)^{13} \approx 1.885649 \]
\( p_0 = 1.1 \)

\[ y[14] = (1.05)^{14} \approx 1.979932 \]
\( p_0 = 1.1 \)

\[ y[15] = (1.05)^{15} \approx 2.078928 \]
$p_0 = 1.1$

\[ y[16] = (1.05)^{16} \approx 2.182875 \]
$p_0 = 1.1$

$y[17] = (1.05)^{17} \approx 2.292018$
$p_0 = 1.1$

$y[18] = (1.05)^{18} \approx 2.406619$
\( p_0 = 1.1 \)

\[
y[19] = (1.05)^{19} \approx 2.526950
\]
Check Yourself!

What value of $p_0$ is associated with the signal below?

0. $p_0 = 0.7$
1. $p_0 = -0.7$
2. $p_0 = 0.7$ interspersed with $p_0 = -0.7$
3. $p_0 = -0.5$
4. $p_0 = 0.5$ interspersed with $p_0 = -0.5$
5. None of the above
Check Yourself!

What value of $p_0$ is associated with the signal below?

0. $p_0 = 0.7$
1. $p_0 = -0.7$
2. $p_0 = 0.7$ interspersed with $p_0 = -0.7$
3. $p_0 = -0.5$
4. $p_0 = 0.5$ interspersed with $p_0 = -0.5$
5. None of the above
Geometric Growth

The value of $p_0$ determines the rate of growth:
Second-order Systems

The unit-sample response of more complicated feedback systems is more complicated.

1. 1.6
2. $1.6 - 0.63$
3. $(1.6)^2 - 0.63$
4. $1.6(1.6 - 0.63)$
5. None of the above
Check Yourself!


1. 1.6
2. $1.6 - 0.63$
3. $(1.6)^2 - 0.63$
4. $1.6(1.6 - 0.63)$
5. None of the above
Second-order Systems

The unit-sample response of more complicated feedback systems is more complicated.
Second-order Systems

The unit-sample response of more complicated feedback systems is more complicated.

Not geometric! Grows, and then decays.
Equivalent Forms

Factor the operator expression to break the system into two simpler systems:

\[ Y = X + 1.6R Y - 0.63 R^2 Y \]
Factor the operator expression to break the system into two simpler systems:

\[ Y = X + 1.6\mathcal{R}Y - 0.63\mathcal{R}^2Y \]

\[ (1 - 1.6\mathcal{R} + 0.63\mathcal{R}^2)Y = X \]
Equivalent Forms

Factor the operator expression to break the system into two simpler systems:

\[ Y = X + 1.6\mathcal{R}Y - 0.63\mathcal{R}^2Y \]

\[ (1 - 1.6\mathcal{R} + 0.63\mathcal{R}^2)Y = X \]

\[ (1 - 0.7\mathcal{R})(1 - 0.9\mathcal{R})Y = X \]
Equivalent Forms

Factored form corresponds to a cascade of simpler systems:

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\[(1 - 0.7\mathcal{R})Y_1 = X \quad (1 - 0.9\mathcal{R})Y = Y_1\]

\[(1 - 0.9\mathcal{R})Y_2 = X \quad (1 - 0.7\mathcal{R})Y = Y_2\]
Equivalent Forms

Even better, the system functional can also be written as a sum of simpler parts:

\[
\frac{Y}{X} = \frac{1}{(1 - 0.9\mathcal{R})(1 - 0.7\mathcal{R})} = \frac{4.5}{1 - 0.9\mathcal{R}} - \frac{3.5}{1 - 0.7\mathcal{R}}
\]
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\]
USR is the **sum** of scaled geometric sequences.

\[
\frac{Y}{X} = \frac{4.5}{1 - 0.9R} - \frac{3.5}{1 - 0.7R}
\]

Let \( x[n] = \delta[n] \)

Then \( y_1[n] = (0.9)^n \) and \( y_2[n] = (0.7)^n \), so

\[
y[n] = 4.5(0.9)^n - 3.5(0.7)^n
\]
Equivalent Forms

USR is the **sum** of scaled geometric sequences.

\[ y_1[n] = 0.7^n \text{ for } n \geq 0 \]

\[ y_2[n] = 0.9^n \text{ for } n \geq 0 \]

\[ y[n] = 4.5(0.9)^n - 3.5(0.7)^n \text{ for } n \geq 0 \]
Finding Poles

Poles can be identified by factoring the denominator of the system functional:

\[
\frac{Y}{X} = \frac{b_0 + b_1 R + b_2 R^2 + \ldots}{1 + a_1 R + a_2 R^2 + \ldots}
\]

\[
\frac{Y}{X} = \frac{b_0 + b_1 R + b_2 R^2 + \ldots}{(1 - p_0 R)(1 - p_1 R)(1 - p_2 R)\ldots}
\]

The poles are the \( p_i \) values. One geometric mode \( p_i^n \) arises from each pole.
Finding Poles

\[
\frac{Y}{X} = \frac{b_0 + b_1 \mathcal{R} + b_2 \mathcal{R}^2 + \ldots}{(1 - p_0 \mathcal{R})(1 - p_1 \mathcal{R})(1 - p_2 \mathcal{R})\ldots}
\]

Partial fraction expansion:

\[
\frac{Y}{X} = \frac{c_0}{1 - p_0 \mathcal{R}} + \frac{c_1}{1 - p_1 \mathcal{R}} + \frac{c_2}{1 - p_2 \mathcal{R}} + \ldots + f_0 + f_1 \mathcal{R} + f_2 \mathcal{R}^2 + \ldots
\]

If the system functional is a proper rational polynomial, then the unit sample response is:

\[
y[n] = c_0 p^n_0 + c_1 p^n_1 + c_2 p^n_2 + \ldots + f_0 + f_1 \mathcal{R} + f_2 \mathcal{R}^2 + \ldots
\]
Finding Poles

\[
\frac{Y}{X} = \frac{b_0 + b_1 \mathcal{R} + b_2 \mathcal{R}^2 + \ldots}{(1 - p_0 \mathcal{R})(1 - p_1 \mathcal{R})(1 - p_2 \mathcal{R})\ldots}
\]

Partial fraction expansion:

\[
\frac{Y}{X} = \frac{c_0}{1 - p_0 \mathcal{R}} + \frac{c_1}{1 - p_1 \mathcal{R}} + \frac{c_2}{1 - p_2 \mathcal{R}} + \ldots + f_0 + f_1 \mathcal{R} + f_2 \mathcal{R}^2 + \ldots
\]

If the system functional is a proper rational polynomial, then the unit sample response is:

\[
y[n] = c_0 p_0^n + c_1 p_1^n + c_2 p_2^n + \ldots
\]
Finding Poles

The poles can also be found by finding the roots of the denominator polynomial after expressing the system functional as a ratio of polynomials in $z = R^{-1}$.

\[
\frac{Y}{X} = \frac{1}{1 - 1.6R + 0.63R^2} = \frac{1}{1 - \frac{1.6}{z} + \frac{0.63}{z^2}} = \frac{z^2}{z^2 - 1.6z + 0.63}
\]

Poles at $z = 0.7$, $z = 0.9$
Long-term Behavior: Dominant Pole

When analyzing systems’ poles, we are interested in long-term behavior (not specific samples).

As $n \to \infty$, how does $y[n]$ behave?

We have seen that a system's unit sample response can be written in the form:

$$y[n] \sim \sum_k c_k p_k^n$$

In the “large-n” case, all poles but the one with the largest magnitude die away, and so looking at the dominant pole alone tells us about the behavior of the system in that case.
Check Yourself!

Consider the system described by:

\[ y[n] = -\frac{1}{4}y[n - 1] + \frac{1}{8}y[n - 2] + x[n - 1] - \frac{1}{2}x[n - 2] \]

How many of the following are true?

1. The unit sample response converges to 0.
2. There are poles at \( z = 0.5 \) and \( z = 0.25 \).
3. There is a pole at \( z = 0.5 \).
4. There are two poles.
5. None of the above.
Check Yourself!

Consider the system described by:

\[ y[n] = -\frac{1}{4}y[n - 1] + \frac{1}{8}y[n - 2] + x[n - 1] - \frac{1}{2}x[n - 2] \]

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4. There are two poles.
5. None of the above.
Wall Finder Revisited

The “bunny” system always has the same behavior \((y[n] \to \infty \text{ as } n \to \infty)\) no matter what. By contrast, our “wall-finder” robot exhibited drastically different behaviors depending on the choice of gain \(k\).

Today: Examine that dependence, develop a means for determining “best” \(k\) analytically.
Wall Finder: Poles

\[ \frac{1}{R} T - k \frac{1}{R} T + 1 \]
Complex Poles

What if a pole has a non-zero imaginary part?

Example:

\[
\frac{Y}{X} = \frac{1}{1 - R + R^2}
\]

Poles at \( z = \frac{1}{2} \pm \frac{\sqrt{3}}{2} j \).

Unit sample response still goes like poles raised to the power \( n \! \).  

Need to understand what happens when complex numbers are raised to integer powers.
Complex Poles

Easiest to understand when poles are represented in polar form:

A number $p_0 = a_0 + b_0 j$ can be represented by a magnitude and an angle in the complex plane:

$$a_0 + b_0 j = r(\cos(\theta) + j \sin(\theta))$$

where $r = \sqrt{a_0^2 + b_0^2}$ and $\theta = \tan^{-1}(b_0, a_0)$

By Euler’s formula:

$$a_0 + b_0 j = re^{j\theta}$$

Furthermore, we can express $(re^{j\theta})^n$ as $r^n e^{jn\theta}$. This is a complex number with magnitude $r^n$ and angle $n\theta$. 
\[ p_0 = 0.98e^{0.2j} \]

\[ y[0] = (0.98)^0 \cdot e^{0.0\cdot0.2j} \approx (1.000000) + (0.000000)j \]
$p_0 = 0.98e^{0.2j}$

$y[1] = (0.98)^1 \cdot e^{1 \cdot 0.2j} \approx (0.960465) + (0.194696)j$
$p_0 = 0.98e^{0.2j}$

$y[2] = (0.98)^2 \cdot e^{2\cdot0.2j} \approx (0.884587) + (0.373997)j$
\[ p_0 = 0.98e^{0.2j} \]

\[ y[3] = (0.98)^3 \cdot e^{3 \cdot 0.2j} \approx (0.776799) + (0.531437)j \]
\[ p_0 = 0.98e^{0.2j} \]

\[ y[4] = (0.98)^4 \cdot e^{4 \cdot 0.2j} \approx (0.642620) + (0.661666)j \]
\( p_0 = 0.98e^{0.2j} \)

\[
y[5] = (0.98)^5 \cdot e^{5 \cdot 0.2j} \approx (0.488390) + (0.760623)j
\]
\[ p_0 = 0.98e^{0.2j} \]

\[ y[6] = (0.98)^6 \cdot e^{6 \cdot 0.2j} \approx (0.320992) + (0.825640)j \]
\[ p_0 = 0.98e^{0.2j} \]

\[ y[7] = (0.98)^7 \cdot e^{7 \cdot 0.2j} \approx (0.147553) + (0.855494)j \]
\( p_0 = 0.98e^{0.2j} \)

\[ y[8] = (0.98)^8 \cdot e^{8 \cdot 0.2j} \approx (-0.024842) + (0.850400)j \]
\[ p_0 = 0.98e^{0.2j} \]

\[ y[9] = (0.98)^9 \cdot e^{9 \cdot 0.2j} \approx (-0.189429) + (0.811943)j \]
\( p_0 = 0.98e^{0.2j} \)

\[ y[10] = (0.98)^{10} \cdot e^{10 \cdot 0.2j} \approx (-0.340022) + (0.742962)j \]
\( p_0 = 0.98e^{0.2j} \)

\[ y[11] = (0.98)^{11} \cdot e^{11 \cdot 0.2j} \approx (-0.471231) + (0.647388)j \]
$p_0 = 0.98e^{0.2j}$

$y[12] = (0.98)^{12} \cdot e^{12 \cdot 0.2j} \approx (-0.578645) + (0.530047)j$
$p_0 = 0.98e^{0.2j}$

$y[13] = (0.98)^{13} \cdot e^{13 \cdot 0.2j} \approx (-0.658967) + (0.396432)j$
$p_0 = 0.98e^{0.2j}$

$y[14] = (0.98)^{14} \cdot e^{14 \cdot 0.2j} \approx (-0.710098) + (0.252461)j$
\[ p_0 = 0.98e^{0.2j} \]

\[ y[15] = (0.98)^{15} \cdot e^{15 \cdot 0.2j} \approx (-0.731178) + (0.104227)j \]
$p_0 = 0.98e^{0.2j}$

$y[16] = (0.98)^{16} \cdot e^{16 \cdot 0.20j} \approx (-0.722563) + (-0.042251)j$
\( p_0 = 0.98e^{0.2j} \)

\[ y[17] = (0.98)^{17} \cdot e^{17 \cdot 0.2j} \approx (-0.685771) + (-0.181261)j \]
\[ p_0 = 0.98e^{0.2j} \]

\[ y[18] = (0.98)^{18} \cdot e^{18 \cdot 0.2j} \approx (-0.623368) + (-0.307612)j \]
$p_0 = 0.98e^{0.2j}$

$y[19] = (0.98)^{19} \cdot e^{19 \cdot 0.2j} \approx (-0.538833) + (-0.416818)j$
\[ p_0 = 0.98e^{0.2j} \]

\[ y[20] = (0.98)^{20} \cdot e^{20 \cdot 0.2j} \approx (-0.436378) + (-0.505247)j \]
\( p_0 = 0.98e^{0.2j} \)

\[
y[21] = (0.98)^{21} \cdot e^{21 \cdot 0.2j} \approx (-0.320756) + (-0.570234)j
\]
\[ p_0 = 0.98e^{0.2j} \]

\[ y[22] = (0.98)^{22} \cdot e^{22 \cdot 0.2j} \approx (-0.197053) + (-0.610139)j \]
$p_0 = 0.98e^{0.2j}$

$y[23] = (0.98)^{23} \cdot e^{23 \cdot 0.2j} \approx (-0.070471) + (-0.624383)j$
\[ p_0 = 0.98e^{0.2j} \]

\[ y[24] = (0.98)^{24} \cdot e^{24 \cdot 0.2j} \approx (0.053880) + (-0.613419)j \]
\[ p_0 = 0.98 e^{0.2j} \]

\[ y[25] = (0.98)^{25} \cdot e^{25\cdot0.2j} \approx (0.171180) + (-0.578677)j \]
\( p_0 = 0.98e^{0.2j} \)

\[ y[26] = (0.98)^{26} \cdot e^{26 \cdot 0.2j} \approx (0.277079) + (-0.522471)j \]
\[ p_0 = 0.98e^{0.2j} \]

\[ y[27] = (0.98)^{27} \cdot e^{27 \cdot 0.2j} \approx (0.367847) + (-0.447869)j \]
\[ p_0 = 0.98e^{0.2j} \]

\[ y[28] = (0.98)^{28} \cdot e^{28 \cdot 0.2j} \approx (0.440503) + (-0.358544)j \]
$p_0 = 0.98e^{0.2j}$

$y[29] = (0.98)^{29} \cdot e^{29 \cdot 0.2j} \approx (0.492895) + (-0.258605)j$
$p_0 = 0.98 e^{0.2j}$

$y[30] = (0.98)^{30} e^{30 \cdot 0.20j} \approx (0.523758) + (-0.152417)j$
\[ p_0 = 0.98e^{0.2j} \]

\[ y[31] = (0.98)^{31} \cdot e^{31 \cdot 0.2j} \approx (0.532726) + (-0.044417)j \]
\[ p_0 = 0.98e^{0.2j} \]

\[ y[32] = (0.98)^{32} \cdot e^{32 \cdot 0.2j} \approx (0.520313) + (0.061058)j \]
\[ p_0 = 0.98e^{0.2j} \]

\[ y[33] = (0.98)^{33} \cdot e^{33 \cdot 0.2j} \approx (0.487855) + (0.159947)j \]
\[ p_0 = 0.98e^{0.2j} \]

\[ y[34] = (0.98)^{34} \cdot e^{34 \cdot 0.20j} \approx (0.437426) + (0.248607)j \]
\[ p_0 = 0.98e^{0.2j} \]

\[ y[35] = (0.98)^{35} \cdot e^{35 \cdot 0.2j} \approx (0.371730) + (0.323943)j \]
\[ p_0 = 0.98e^{0.2j} \]

\[ y[36] = (0.98)^{36} \cdot e^{36 \cdot 0.2j} \approx (0.293963) + (0.383511)j \]
\[ p_0 = 0.98e^{0.2j} \]

\[ y[37] = (0.98)^{37} \cdot e^{37 \cdot 0.2j} \approx (0.207674) + (0.425582)j \]
$p_0 = 0.98e^{0.2j}$

$y[38] = (0.98)^{38} \cdot e^{38 \cdot 0.2j} \approx (0.116604) + (0.449190)j$
\[ p_0 = 0.98e^{0.2j} \]

\[ y[39] = (0.98)^{39} \cdot e^{39 \cdot 0.2j} \approx (0.024539) + (0.454134)j \]
\( p_0 = 0.98e^{0.2j} \)

\[ y[40] = (0.98)^{40} \cdot e^{40 \cdot 0.2j} \approx (-0.064849) + (0.440957)j \]
\( p_0 = 0.98e^{0.2j} \)

\[ y[41] = (0.98)^{41} \cdot e^{41 \cdot 0.2j} \approx (-0.148138) + (0.410898)j \]
\[ p_0 = 0.98e^{0.2j} \]

\[ y[42] = (0.98)^{42} \cdot e^{42 \cdot 0.2j} \approx (-0.222282) + (0.365812)j \]
\( p_0 = 0.98e^{0.2j} \)

\[ y[43] = (0.98)^{43} \cdot e^{43 \cdot 0.2j} \approx (-0.284716) + (0.308072)j \]
\[ p_0 = 0.98 e^{0.2j} \]

\[ y[44] = (0.98)^{44} \cdot e^{44 \cdot 0.2j} \approx (-0.333440) + (0.240459)j \]
\[ p_0 = 0.98e^{0.2j} \]

\[ y[45] = (0.98)^{45} \cdot e^{45 \cdot 0.2j} \approx (-0.367074) + (0.166033)j \]
\( p_0 = 0.98e^{0.2j} \)

\[ y[46] = (0.98)^{46} \cdot e^{46 \cdot 0.2j} \approx (-0.384888) + (0.088001)j \]
\( p_0 = 0.98 e^{0.2j} \)

\[ y[47] = (0.98)^{47} \cdot e^{47 \cdot 0.2j} \approx (-0.386805) + (0.009586) j \]
$p_0 = 0.98e^{0.2j}$

$y[48] = (0.98)^{48} \cdot e^{48 \cdot 0.2j} \approx (-0.373379) + (-0.066102)j$
$p_0 = 0.98e^{0.2j}$

$y[49] = (0.98)^{49} \cdot e^{49 \cdot 0.2j} \approx (-0.345748) + (-0.136184)j$
\[ p_0 = 0.98e^{0.2j} \]

\[ y[50] = (0.98)^{50} \cdot e^{50 \cdot 0.2j} \approx (-0.305564) + (-0.198116)j \]
\[ p_0 = 0.98e^{0.2j} \]

\[ y[51] = (0.98)^{51} \cdot e^{51 \cdot 0.2j} \approx (-0.254912) + (-0.249776)j \]
\[ p_0 = 0.98e^{0.2j} \]

\[ y[52] = (0.98)^{52} \cdot e^{52 \cdot 0.2j} \approx (-0.196203) + (-0.289531)j \]
$p_0 = 0.98e^{0.2j}$

$y[53] = (0.98)^{53} \cdot e^{53 \cdot 0.2j} \approx (-0.132076) + (-0.316285)j$
$p_0 = 0.98e^{0.2j}$

$y[54] = (0.98)^{54} \cdot e^{54 \cdot 0.2j} \approx (-0.065275) + (-0.329495)j$
\[ p_0 = 0.98e^{0.2j} \]

\[ y[55] = (0.98)^{55} \cdot e^{55 \cdot 0.2j} \approx (0.001457) + (-0.329177)j \]
\[ p_0 = 0.98e^{0.2j} \]

\[ y[56] = (0.98)^{56} \cdot e^{56 \cdot 0.2j} \approx (0.065489) + (-0.315880)j \]
\[ p_0 = 0.98 e^{0.2j} \]

\[ y[57] = (0.98)^{57} \cdot e^{57 \cdot 0.2j} \approx (0.124400) + (-0.290641)j \]
$p_0 = 0.98e^{0.2j}$

$y[58] = (0.98)^{58} \cdot e^{58 \cdot 0.2j} \approx (0.176069) + (-0.254930)j$
$p_0 = 0.98e^{0.2j}$

$y[59] = (0.98)^{59} \cdot e^{59 \cdot 0.2j} \approx (0.218742) + (-0.210572)j$
\[ p_0 = 0.98e^{0.2j} \]

\[ y[60] = (0.98)^{60} \cdot e^{60 \cdot 0.2j} \approx (0.251091) + (-0.159659)j \]
\( p_0 = 0.98e^{0.2j} \)

\[
y[61] = (0.98)^{61} \cdot e^{61 \cdot 0.2j} \approx (0.272250) + (-0.104460)j
\]
\[ p_0 = 0.98e^{0.2j} \]

\[ y[62] = (0.98)^{62} \cdot e^{62 \cdot 0.2j} \approx (0.281824) + (-0.047325)j \]
\[ p_0 = 0.98e^{0.2j} \]

\[ y[63] = (0.98)^{63} \cdot e^{63 \cdot 0.2j} \approx (0.279896) + (0.009416)j \]
\[ p_0 = 0.98e^{0.2j} \]

\[ y[64] = (0.98)^{64} \cdot e^{64 \cdot 0.2j} \approx (0.266997) + (0.063539)j \]
$p_0 = 0.98e^{0.2j}$

$y[65] = (0.98)^{65} \cdot e^{65 \cdot 0.2j} \approx (0.244071) + (0.113010)j$
\[ p_0 = 0.98 e^{0.2j} \]

\[ y[66] = (0.98)^{66} \cdot e^{66 \cdot 0.2j} \approx (0.212419) + (0.156062)j \]
\[ p_0 = 0.98e^{0.2j} \]

\[ y[67] = (0.98)^{67} \cdot e^{67 \cdot 0.2j} \approx (0.173637) + (0.191249)j \]
\( p_0 = 0.98e^{0.2j} \)

\( y[68] = (0.98)^{68} \cdot e^{68 \cdot 0.2j} \approx (0.129536) + (0.217494)j \)
\( p_0 = 0.98e^{0.2j} \)

\[ y[69] = (0.98)^{69} \cdot e^{69 \cdot 0.2j} \approx (0.082070) + (0.234116)j \]
\( p_0 = 0.98e^{0.2j} \)

\[ y[70] = (0.98)^{70} \cdot e^{70 \cdot 0.2j} \approx (0.033244) + (0.240839)j \]
\[ p_0 = 0.98e^{0.2j} \]

\[ y[71] = (0.98)^{71} \cdot e^{71 \cdot 0.20j} \approx (-0.014961) + (0.237790)j \]
\[ p_0 = 0.98e^{0.2j} \]

\[ y[72] = (0.98)^{72} \cdot e^{72 \cdot 0.2j} \approx (-0.060666) + (0.225476)j \]
$p_0 = 0.98 e^{0.2j}$

$y[73] = (0.98)^{73} \cdot e^{73 \cdot 0.2j} \approx (-0.102167) + (0.204751) j$
\[ p_0 = 0.98e^{0.2j} \]

\[ y[74] = (0.98)^{74} \cdot e^{74 \cdot 0.2j} \approx (-0.137992) + (0.176764)j \]
$p_0 = 0.98e^{0.2j}$

$y[75] = (0.98)^{75} \cdot e^{75 \cdot 0.2j} \approx (-0.166952) + (0.142910)j$
\[ p_0 = 0.98e^{0.2j} \]

\[ y[76] = (0.98)^{76} \cdot e^{76 \cdot 0.2j} \approx (-0.188175) + (0.104755)j \]
\[ \rho_0 = 0.98e^{0.2j} \]

\[ y[77] = (0.98)^{77} \cdot e^{77 \cdot 0.2j} \approx (-0.201131) + (0.063976)j \]
\[ p_0 = 0.98e^{0.2j} \]

\[ y[78] = (0.98)^{78} \cdot e^{78 \cdot 0.2j} \approx (-0.205635) + (0.022288)j \]
\[ p_0 = 0.98e^{0.2j} \]

\[ y[79] = (0.98)^{79} \cdot e^{79 \cdot 0.2j} \approx (-0.201845) + (-0.018630)j \]
\[ p_0 = 0.98e^{0.2j} \]

\[ y[80] = (0.98)^{80} \cdot e^{80 \cdot 0.2j} \approx (-0.190238) + (-0.057192)j \]
\[ p_0 = 0.98e^{0.2j} \]

\[ y[81] = (0.98)^{81} \cdot e^{81 \cdot 0.2j} \approx (-0.171582) + (-0.091969)j \]
\[ p_0 = 0.98 e^{0.2j} \]

\[ y[82] = (0.98)^{82} \cdot e^{82 \cdot 0.2j} \approx (-0.146892) + (-0.121739)j \]
\[ p_0 = 0.98e^{0.2j} \]

\[ y[83] = (0.98)^{83} \cdot e^{83 \cdot 0.2j} \approx (-0.117383) + (-0.145526)j \]
$p_0 = 0.98e^{0.2j}$

$y[84] = (0.98)^{84} \cdot e^{84 \cdot 0.20j} \approx (-0.084409) + (-0.162627)j$
\[ p_0 = 0.98e^{0.2j} \]

\[ y[85] = (0.98)^{85} \cdot e^{85 \cdot 0.2j} \approx (-0.049409) + (-0.172631)j \]
$p_0 = 0.98e^{0.2j}$

$y[86] = (0.98)^{86} \cdot e^{86 \cdot 0.2j} \approx (-0.013845) + (-0.175426)j$
\[ p_0 = 0.98e^{0.2j} \]

\[ y[87] = (0.98)^{87} \cdot e^{87 \cdot 0.20j} \approx (0.020857) + (-0.171186)j \]
\[ p_0 = 0.98e^{0.2j} \]

\[ y[88] = (0.98)^{88} \cdot e^{88 \cdot 0.2j} \approx (0.053362) + (-0.160358)j \]
$p_0 = 0.98e^{0.2j}$

$y[89] = (0.98)^{89} \cdot e^{89 \cdot 0.2j} \approx (0.082473) + (-0.143629)j$
\[ p_0 = 0.98 e^{0.2j} \]

\[ y[90] = (0.98)^{90} \cdot e^{0.90 \cdot 0.2j} \approx (0.107176) + (-0.121893)j \]
\[ p_0 = 0.98e^{0.2j} \]

\[ y[91] = (0.98)^{91} \cdot e^{91 \cdot 0.2j} \approx (0.126671) + (-0.096207)j \]
\[ p_0 = 0.98e^{0.2j} \]

\[ y[92] = (0.98)^{92} \cdot e^{92 \cdot 0.20j} \approx (0.140395) + (-0.067741)j \]
\[ p_0 = 0.98e^{0.2j} \]

\[ y[93] = (0.98)^{93} \cdot e^{93 \cdot 0.2j} \approx (0.148033) + (-0.037729)j \]
\[ p_0 = 0.98e^{0.2j} \]

\[ y[94] = (0.98)^{94} \cdot e^{94 \cdot 0.2j} \approx (0.149526) + (-0.007416)j \]
$p_0 = 0.98e^{0.2j}$

$y[95] = (0.98)^{95} \cdot e^{95 \cdot 0.2j} \approx (0.145059) + (0.021989)j$
$p_0 = 0.98e^{0.2j}$

$y[96] = (0.98)^{96} \cdot e^{96 \cdot 0.2j} \approx (0.135043) + (0.049362)j$
\[ p_0 = 0.98e^{0.2j} \]

\[ y[97] = (0.98)^{97} \cdot e^{97 \cdot 0.2j} \approx (0.120093) + (0.073703)j \]
\[ p_0 = 0.98 e^{0.2j} \]

\[ y[98] = (0.98)^{98} \cdot e^{98 \cdot 0.2j} \approx (0.100996) + (0.094171)j \]
\[ p_0 = 0.98e^{0.2j} \]

\[ y[99] = (0.98)^{99} \cdot e^{99 \cdot 0.2j} \approx (0.078668) + (0.110111)j \]
\[ p_0 = 1.01 e^{0.2j} \]

\[ y[0] = (1.01)^0 \cdot e^{0.20j} \approx (1.000000) + (0.000000)j \]
\( p_0 = 1.01 e^{0.2j} \)

\[ y[1] = (1.01)^1 \cdot e^{1 \cdot 0.20j} \approx (0.989867) + (0.200656)j \]
$p_0 = 1.01e^{0.2j}$

$y[2] = (1.01)^2 \cdot e^{2 \cdot 0.2j} \approx (0.939574) + (0.397246)j$
\[ p_0 = 1.01e^{0.2j} \]

\[ y[3] = (1.01)^3 \cdot e^{3 \cdot 0.2j} \approx (0.850344) + (0.581752)j \]
\[ p_0 = 1.01e^{0.2j} \]

\[ y[4] = (1.01)^4 \cdot e^{4 \cdot 0.20j} \approx (0.724996) + (0.746484)j \]
\[ p_0 = 1.01e^{0.2j} \]

\[ y[5] = (1.01)^5 \cdot e^{5 \cdot 0.2j} \approx (0.567863) + (0.884394)j \]
\[ p_0 = 1.01e^{0.2j} \]

\[ y[6] = (1.01)^6 \cdot e^{6 \cdot 0.2j} \approx (0.384650) + (0.989378)j \]
\( p_0 = 1.01e^{0.2j} \)

\[
y[7] = (1.01)^7 \cdot e^{7\cdot0.20j} \approx (0.182228) + (1.056535)j
\]
\( p_0 = 1.01e^{0.2j} \)

\[ y[8] = (1.01)^8 \cdot e^{8 \cdot 0.2j} \approx (-0.031619) + (1.082395)j \]
$p_0 = 1.01e^{0.2j}$

$y[9] = (1.01)^9 \cdot e^{9 \cdot 0.2j} \approx (-0.248488) + (1.065083)j$
\[ p_0 = 1.01 e^{0.2j} \]

\[ y[10] = (1.01)^{10} \cdot e^{10 \cdot 0.2j} \approx (-0.459685) + (1.004430)j \]
\[ p_0 = 1.01e^{0.2j} \]

\[ y[11] = (1.01)^{11} \cdot e^{11 \cdot 0.2j} \approx (-0.656572) + (0.902014)j \]
\[ p_0 = 1.01e^{0.2j} \]

\[ y[12] = (1.01)^{12} \cdot e^{12 \cdot 0.20j} \approx (-0.830914) + (0.761129)j \]
$p_0 = 1.01e^{0.2j}$

$y[13] = (1.01)^{13} \cdot e^{13 \cdot 0.2j} \approx (-0.975219) + (0.586689)j$
\[ p_0 = 1.01 e^{0.2j} \]

\[ y[14] = (1.01)^{14} \cdot e^{14 \cdot 0.2j} \approx (-1.083060) + (0.385060)j \]
$p_0 = 1.01 e^{0.2j}$

$y[15] = (1.01)^{15} \cdot e^{15 \cdot 0.2j} \approx (-1.149351) + (0.163836)j$
\[ p_0 = 1.01 e^{0.2j} \]

\[ y[16] = (1.01)^{16} \cdot e^{16 \cdot 0.2j} \approx (-1.170579) + (-0.068448)j \]
\[ p_0 = 1.01 e^{0.2j} \]
\[ y[17] = (1.01)^{17} \cdot e^{17 \cdot 0.2j} \approx (-1.144983) + (-0.302638)j \]
\[ p_0 = 1.01e^{0.2j} \]

\[ y[18] = (1.01)^{18} \cdot e^{18 \cdot 0.2j} \approx (-1.072655) + (-0.529320)j \]
\( p_0 = 1.01e^{0.2j} \)

\[ y[19] = (1.01)^{19} \cdot e^{19 \cdot 0.2j} \approx (-0.955575) + (-0.739191)j \]
\( p_0 = 1.01 e^{0.2j} \)

\[ y[20] = (1.01)^{20} \cdot e^{20 \cdot 0.2j} \approx (-0.797569) + (-0.923443)j \]
$p_0 = 1.01e^{0.2j}$

$y[21] = (1.01)^{21} \cdot e^{21 \cdot 0.2j} \approx (-0.604193) + (-1.074123)j$
\[ p_0 = 1.01e^{0.2j} \]

\[ y[22] = (1.01)^{22} \cdot e^{22 \cdot 0.20j} \approx (-0.382542) + (-1.184474)j \]
$p_0 = 1.01e^{0.2j}$

$y[23] = (1.01)^{23} \cdot e^{23 \cdot 0.2j} \approx (-0.140994) + (-1.249232)j$
\( p_0 = 1.01 e^{0.2j} \)

\[ y[24] = (1.01)^{24} \cdot e^{24 \cdot 0.2j} \approx (0.111100) + (-1.264865)j \]
\[ p_0 = 1.01e^{0.2j} \]

\[ y[25] = (1.01)^{25} \cdot e^{25 \cdot 0.2j} \approx (0.363777) + (-1.229755)j \]
\[ p_0 = 1.01e^{0.2j} \]

\[ y[26] = (1.01)^{26} \cdot e^{26 \cdot 0.2j} \approx (0.606849) + (-1.144300)j \]
\[ p_0 = 1.01e^{0.2j} \]

\[ y[27] = (1.01)^{27} \cdot e^{27 \cdot 0.2j} \approx (0.830311) + (-1.010937)j \]
\[ p_0 = 1.01e^{0.2j} \]

\[ y[28] = (1.01)^{28} \cdot e^{28 \cdot 0.2j} \approx (1.024748) + (-0.834087)j \]
\( p_0 = 1.01e^{0.2j} \)

\[ y[29] = (1.01)^{29} \cdot e^{29 \cdot 0.2j} \approx (1.181729) + (-0.620013)j \]
\[ p_0 = 1.01e^{0.2j} \]

\[ y[30] = (1.01)^{30} \cdot e^{30 \cdot 0.2j} \approx (1.294164) + (-0.376610)j \]
\[ p_0 = 1.01e^{0.2j} \]

\[ y[31] = (1.01)^{31} \cdot e^{31 \cdot 0.2j} \approx (1.356620) + (-0.113112)j \]
\( p_0 = 1.01e^{0.2j} \)

\[ y[32] = (1.01)^{32} \cdot e^{32 \cdot 0.2j} \approx (1.365570) + (0.160248)j \]
\[ p_0 = 1.01e^{0.2j} \]

\[ y[33] = (1.01)^3 \cdot e^{3 \cdot 0.2j} \approx (1.319579) + (0.432634)j \]
\[ p_0 = 1.01e^{0.2j} \]

\[ y^{[34]} = (1.01)^{34} \cdot e^{34 \cdot 0.2j} \approx (1.219397) + (0.693032)j \]
\[ p_0 = 1.01e^{0.2j} \]

\[ y[35] = (1.01)^{35} \cdot e^{35 \cdot 0.2j} \approx (1.067980) + (0.930689)j \]
$p_0 = 1.01e^{0.2j}$

$y[36] = (1.01)^{36} \cdot e^{36 \cdot 0.2j} \approx (0.870410) + (1.135555)j$
\[ p_0 = 1.01 e^{0.2j} \]

\[ y[37] = (1.01)^{37} \cdot e^{37 \cdot 0.2j} \approx (0.633734) + (1.298702)j \]
\( p_0 = 1.01e^{0.2j} \)

\[ y[38] = (1.01)^{38} \cdot e^{38 \cdot 0.2j} \approx (0.366721) + (1.412705)j \]
\( p_0 = 1.01e^{0.2j} \)

\[ y[39] = (1.01)^{39} \cdot e^{39\cdot0.2j} \approx (0.079537) + (1.471975)j \]
$p_0 = 1.01e^{0.2j}$

$y[40] = (1.01)^{40} \cdot e^{40 \cdot 0.20j} \approx (-0.216630) + (1.473020)j$
\[ p_0 = 1.01e^{0.2j} \]

\[ y[41] = (1.01)^{41} \cdot e^{41 \cdot 0.2j} \approx (-0.510005) + (1.414626)j \]
$p_0 = 1.01 e^{0.2j}$

$y[42] = (1.01)^{42} \cdot e^{42 \cdot 0.20j} \approx (-0.788690) + (1.297956)j$
\[ p_0 = 1.01 e^{0.2j} \]

\[ y[43] = (1.01)^{43} \cdot e^{43 \cdot 0.2j} \approx (-1.041141) + (1.126549)j \]
\[ p_0 = 1.01e^{0.2j} \]

\[ y[44] = (1.01)^{44} \cdot e^{44 \cdot 0.2j} \approx (-1.256641) + (0.906222)j \]
\[ p_0 = 1.01e^{0.2j} \]

\[ y[45] = (1.01)^{45} \cdot e^{45 \cdot 0.2j} \approx (-1.425746) + (0.644887)j \]
\[ p_0 = 1.01e^{0.2j} \]

\[ y[46] = (1.01)^{46} \cdot e^{46 \cdot 0.2j} \approx (-1.540700) + (0.352268)j \]
\[ p_0 = 1.01e^{0.2j} \]

\[ y[47] = (1.01)^{47} \cdot e^{47 \cdot 0.2j} \approx (-1.595773) + (0.039548)j \]
\( p_0 = 1.01e^{0.2j} \)

\[
y[48] = (1.01)^{48} \cdot e^{48 \cdot 0.2j} \approx (-1.587539) + (-0.281054)j
\]
\[ p_0 = 1.01e^{0.2j} \]

\[ y[49] = (1.01)^{49} \cdot e^{49 \cdot 0.2j} \approx (-1.515058) + (-0.596756)j \]
\[ p_0 = 1.01e^{0.2j} \]

\[ y[50] = (1.01)^{50} \cdot e^{50 \cdot 0.2j} \approx (-1.379964) + (-0.894714)j \]
$p_0 = 1.01 e^{0.2j}$

$y[51] = (1.01)^{51} \cdot e^{51 \cdot 0.2j} \approx (-1.186451) + (-1.162547)j$
\[ p_0 = 1.01 e^{0.2j} \]

\[ y[52] = (1.01)^{52} \cdot e^{52 \cdot 0.2j} \approx (-0.941157) + (-1.388835)j \]
$p_0 = 1.01e^{0.2j}$

$y[53] = (1.01)^{53} \cdot e^{53 \cdot 0.20j} \approx (-0.652942) + (-1.563611)j$
\[ p_0 = 1.01e^{0.2j} \]

\[ y[54] = (1.01)^{54} \cdot e^{54 \cdot 0.2j} \approx (-0.332578) + (-1.678785)j \]
\[ p_0 = 1.01e^{0.2j} \]

\[ y[55] = (1.01)^{55} \cdot e^{55 \cdot 0.2j} \approx (0.007650) + (-1.728508)j \]
\[ p_0 = 1.01e^{0.2j} \]

\[ y[56] = (1.01)^{56} \cdot e^{56 \cdot 0.2j} \approx (0.354408) + (-1.709458)j \]
\[ p_0 = 1.01e^{0.2j} \]

\[ y[57] = (1.01)^{57} \cdot e^{57 \cdot 0.2j} \approx (0.693830) + (-1.621022)j \]
$p_0 = 1.01e^{0.2j}$

$y[58] = (1.01)^{58} \cdot e^{58 \cdot 0.2j} \approx (1.012067) + (-1.465376)j$
\( p_0 = 1.01 e^{0.2j} \)

\[
y[59] = (1.01)^{59} \cdot e^{59 \cdot 0.2j} \approx (1.295849) + (-1.247450)j
\]
\[ p_0 = 1.01e^{0.2j} \]

\[ y[60] = (1.01)^{60} \cdot e^{60 \cdot 0.2j} \approx (1.533027) + (-0.974790)j \]
\( p_0 = 1.01 e^{0.2j} \)

\[ y[61] = (1.01)^{61} \cdot e^{61\cdot0.2j} \approx (1.713090) + (-0.657302)j \]
$p_0 = 1.01e^{0.2j}$

$y[62] = (1.01)^{62} \cdot e^{62 \cdot 0.2j} \approx (1.827624) + (-0.306900)j$
\[ p_0 = 1.01e^{0.2j} \]

\[ y[63] = (1.01)^{63} \cdot e^{63 \cdot 0.20j} \approx (1.870686) + (0.062934)j \]
\[ p_0 = 1.01e^{0.2j} \]

\[ y[64] = (1.01)^{64} \cdot e^{64 \cdot 0.20j} \approx (1.839103) + (0.437660)j \]
\[ p_0 = 1.01e^{0.2j} \]

\[ y[65] = (1.01)^{65} \cdot e^{65 \cdot 0.2j} \approx (1.732648) + (0.802253)j \]
\[ p_0 = 1.01e^{0.2j} \]

\[ y[66] = (1.01)^{66} \cdot e^{66 \cdot 0.2j} \approx (1.554115) + (1.141790)j \]
\[ p_0 = 1.01 e^{0.2j} \]

\[ y[67] = (1.01)^{67} \cdot e^{67 \cdot 0.2j} \approx (1.309261) + (1.442063)j \]
\( p_0 = 1.01 e^{0.2j} \)

\[ y[68] = (1.01)^{68} \cdot e^{68 \cdot 0.2j} \approx (1.006635) + (1.690162)j \]
\( p_0 = 1.01 e^{0.2j} \)

\[ y[69] = (1.01)^{69} \cdot e^{69 \cdot 0.2j} \approx (0.657294) + (1.875024)j \]
\( p_0 = 1.01e^{0.2j} \)

\[ y[70] = (1.01)^{70} \cdot e^{70 \cdot 0.2j} \approx (0.274399) + (1.987915)j \]
$p_0 = 1.01e^{0.2j}$

$y[71] = (1.01)^{71} \cdot e^{71 \cdot 0.2j} \approx (-0.127268) + (2.022831)j$
\[ p_0 = 1.01e^{0.2j} \]

\[ y[72] = (1.01)^{72} \cdot e^{72 \cdot 0.20j} \approx (-0.531872) + (1.976797)j \]
\[ p_0 = 1.01e^{0.2j} \]

\[ y[73] = (1.01)^{73} \cdot e^{73 \cdot 0.2j} \approx (-0.923139) + (1.850044)j \]
\[ p_0 = 1.01e^{0.2j} \]

\[ y[74] = (1.01)^{74} \cdot e^{74 \cdot 0.20j} \approx (-1.285007) + (1.646064)j \]
\[ p_0 = 1.01e^{0.2j} \]

\[ y[75] = (1.01)^{75} \cdot e^{75 \cdot 0.20j} \approx (-1.602279) + (1.371541)j \]
\[ p_0 = 1.01 e^{0.2j} \]

\[ y[76] = (1.01)^{76} \cdot e^{76 \cdot 0.20j} \approx (-1.861252) + (1.036136)j \]
\[ p_0 = 1.01 e^{0.2j} \]

\[ y[77] = (1.01)^{77} \cdot e^{77 \cdot 0.20j} \approx (-2.050299) + (0.652166)j \]
\[ p_0 = 1.01e^{0.2j} \]

\[ y[78] = (1.01)^{78} \cdot e^{78 \cdot 0.2j} \approx (-2.160385) + (0.234153)j \]
\[ p_0 = 1.01e^{0.2j} \]

\[ y[79] = (1.01)^{79} \cdot e^{79 \cdot 0.2j} \approx (-2.185478) + (-0.201714)j \]
\[ p_0 = 1.01e^{0.2j} \]

\[ y[80] = (1.01)^{80} \cdot e^{80 \cdot 0.20j} \approx (-2.122858) + (-0.638200)j \]
\[ p_0 = 1.01e^{0.2j} \]
\[ y[81] = (1.01)^{81} \cdot e^{81 \cdot 0.2j} \approx (-1.973289) + (-1.057697)j \]
\[ p_0 = 1.01e^{0.2j} \]

\[ y[82] = (1.01)^{82} \cdot e^{82 \cdot 0.2j} \approx (-1.741061) + (-1.442932)j \]
\[ p_0 = 1.01e^{0.2j} \]

\[ y[83] = (1.01)^{83} \cdot e^{83 \cdot 0.20j} \approx (-1.433886) + (-1.777666)j \]
\[ p_0 = 1.01 e^{0.2 j} \]

\[ y[84] = (1.01)^{84} \cdot e^{84 \cdot 0.2 j} \approx (-1.062658) + (-2.047371) j \]
\( p_0 = 1.01 e^{0.2j} \)

\[ y[85] = (1.01)^{85} \cdot e^{85 \cdot 0.2j} \approx (-0.641073) + (-2.239854)j \]
\[ p_0 = 1.01e^{0.2j} \]

\[ y[86] = (1.01)^{86} \cdot e^{86 \cdot 0.2j} \approx (-0.185137) + (-2.345793)j \]
\[ p_0 = 1.01 e^{0.2j} \]

\[ y[87] = (1.01)^{87} \cdot e^{87 \cdot 0.20j} \approx (0.287437) + (-2.359173)j \]
\[ p_0 = 1.01e^{0.2j} \]

\[ y[88] = (1.01)^{88} \cdot e^{88 \cdot 0.2j} \approx (0.757907) + (-2.277592)j \]
\[ p_0 = 1.01e^{0.2j} \]

\[ y[89] = (1.01)^{89} \cdot e^{89 \cdot 0.2j} \approx (1.207239) + (-2.102435)j \]
\[ p_0 = 1.01e^{0.2j} \]

\[ y[90] = (1.01)^{90} \cdot e^{90 \cdot 0.2j} \approx (1.616873) + (-1.838892)j \]
\[ p_0 = 1.01 e^{0.2j} \]

\[ y[91] = (1.01)^{91} \cdot e^{91 \cdot 0.2j} \approx (1.969474) + (-1.495824)j \]
\[ p_0 = 1.01 e^{0.2j} \]

\[ y[92] = (1.01)^{92} \cdot e^{92 \cdot 0.2j} \approx (2.249664) + (-1.085480)j \]
\[ p_0 = 1.01 e^{0.2j} \]

\[ y[93] = (1.01)^{93} \cdot e^{93 \cdot 0.2j} \approx (2.444677) + (-0.623072)j \]
$p_0 = 1.01e^{0.2j}$

$y[94] = (1.01)^{94} \cdot e^{94 \cdot 0.2j} \approx (2.544929) + (-0.126220)j$
\[ p_0 = 1.01e^{0.2j} \]

\[ y[95] = (1.01)^{95} \cdot e^{95 \cdot 0.2j} \approx (2.544468) + (0.385715)j \]
\[ p_0 = 1.01e^{0.2j} \]

\[ y[96] = (1.01)^{96} \cdot e^{96 \cdot 0.2j} \approx (2.441290) + (0.892369)j \]
\[ p_0 = 1.01e^{0.2j} \]

\[ y[97] = (1.01)^{97} \cdot e^{97 \cdot 0.20j} \approx (2.237494) + (1.373187)j \]
\[ p_0 = 1.01e^{0.2j} \]

\[ y[98] = (1.01)^{98} \cdot e^{98 \cdot 0.2j} \approx (1.939284) + (1.808239)j \]
\[ p_0 = 1.01e^{0.2j} \]

\[ y[99] = (1.01)^{99} \cdot e^{99 \cdot 0.2j} \approx (1.556799) + (2.179046)j \]
Complex Poles

Complex poles, but real-valued response. This happens because poles come in complex conjugate pairs (summing $p_0^n + p_1^n$ yields a real number if $p_0$ and $p_1$ are complex conjugates).

The period of oscillation of the resulting real-valued signal is the same as the periods of the complex-valued signals!
\[ p_0 = 0.98e^{\pm 0.2j} \]
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Check Yourself!

Output of a system with poles at $z = re^{\pm j\omega}$

Which statement is true?

1. $r < 0.5$ and $\omega \approx 0.5$
2. $0.5 < r < 1$ and $\omega \approx 0.5$
3. $r < 0.5$ and $\omega \approx 0.08$
4. $0.5 < r < 1$ and $\omega \approx 0.08$
5. None of the above
Check Yourself!

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Which statement is true?

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4. $0.5 < r < 1$ and $\omega \approx 0.08$
5. None of the above
Poles for Design

The **poles** of the system tell us something about how we expect it to behave in the long term.

By adjusting $k$, we change the poles of the system.

Our design problem can be thought of as choosing $k$ to move the poles to a “desirable” location in the complex plane.
Summary

Feedback → cyclic signal flow paths

Cyclic paths → persistant responses to transient inputs

We can characterize persistent responses with poles

Poles provide a way to characterize the behavior of a system in terms of a mathematical description as a system functional

Poles provide a way to reason about the long-term behavior of a system

**Powerful Representations** (here polynomials) lead to **powerful abstractions** (e.g., poles)
Bunnies
Bunnies
Bunnies
Bunnies
Check Yourself!

Define new signals $A$ and $C$, representing adults and children, respectively, from internal sources.

On each timestep, the number of children:
$C = RA + X$

On each timestep, the number of adults:
$A = R(A + C)$
Check Yourself!

Define new signals $A$ and $C'$, representing adults and children, respectively, from internal sources.

On each timestep, the number of children:
$C = RA + X$

On each timestep, the number of adults:
$A = R(A + C')$

$Y = A + C'$
$Y = R(A + C') + RA + X$
$Y = R(A + C') + R^2(A + C') + X$
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On each timestep, the number of children:
\[ C = RA + X \]

On each timestep, the number of adults:
\[ A = R(A + C) \]

\[ Y = A + C \]
\[ Y = R(A + C) + RA + X \]
\[ Y = R(A + C) + R^2(A + C) + X \]
\[ Y = RY + R^2Y + X \]
Fibonacci!

```python
>>> from functools import reduce
>>> fib=lambda n:reduce(lambda x,n: [x[1],x[0]+x[1]],range(n),[0,1])[1]
>>> fib(0)
1
>>> fib(1)
1
>>> fib(2)
2
>>> fib(3)
3
>>> fib(4)
5
>>> fs = [fib(i) for i in range(30)]
>>> fs[:12]
[1, 1, 2, 3, 5, 8, 13, 21, 34, 55, 89, 144]
>>> fr = [j/i for i,j in zip(fs,fs[1:])]  
>>> fr
[1.0, 2.0, 1.5, 1.6666666666666666, 1.6, 1.625, 1.6153846153846154, 1.619047619047619, 1.6176470588235294, 1.6153846153846154, 1.6181818181818182]  
```
Bunnies Revisited

\[ Y = RY + R^2Y + X \]
Bunnies Revisited

\[ Y = RY + R^2Y + X \]

\[ \frac{Y}{X} = \frac{1}{1 - R - R^2} \]
Bunnies Revisited

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\[
\frac{Y}{X} = \frac{1}{1 - \frac{1}{z} - \frac{1}{z^2}}
\]
Bunnies Revisited

\[ Y = \mathcal{R}Y + \mathcal{R}^2Y + X \]

\[ \frac{Y}{X} = \frac{1}{1 - \mathcal{R} - \mathcal{R}^2} \]

\[ \frac{Y}{X} = \frac{1}{1 - \frac{1}{z} - \frac{1}{z^2}} \]

\[ \frac{Y}{X} = \frac{z^2}{z^2 - z - 1} \]
Bunnies Revisited

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\[ \frac{Y}{X} = \frac{z^2}{z^2 - z - 1} \]

\[ p_0, p_1 = \frac{1 \pm \sqrt{5}}{2} \]
Recall that the USR of the composite system can be represented as:

\[ y[n] = \sum_i c_i p_i^n \]
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Poles at:

\[ \phi_+ = \frac{1+\sqrt{5}}{2} \approx 1.618 \quad \phi_- = \frac{1-\sqrt{5}}{2} \approx -0.618 \]
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Two modes:
Bunnies Revisited

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Poles at:

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Two modes:
Bunnies Revisited

What if we want to find the response exactly?

\[ y[n] = c_0(\phi_+^n) + c_1(\phi_-^n) \]

Two unknowns, and so need two equations.
Bunnies Revisited

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Two unknowns, and so need two equations.

\[ y[0] = 1 = c_0(\phi_0^0) + c_1(\phi_0^0) = c_0 + c_1 \]
\[ y[1] = 1 = c_0(\phi_1^1) + c_1(\phi_1^1) = c_0\phi_+ + c_1\phi_- \]
Bunnies Revisited

What if we want to find the response exactly?

\[ y[n] = c_0(\phi^n_+) + c_1(\phi_n^-) \]

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\[ y[1] = 1 = c_0(\phi^1_+) + c_1(\phi^1_-) = c_0\phi_+ + c_1\phi_- \]

Solving:

\[ c_0 = \frac{1 + \sqrt{5}}{2\sqrt{5}} \quad c_1 = \frac{\sqrt{5} - 1}{2\sqrt{5}} \]
Bunnies Revisited

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\[ c_0 = \frac{1+\sqrt{5}}{2\sqrt{5}} \quad \quad c_1 = \frac{\sqrt{5}-1}{2\sqrt{5}} \]

\[ \text{fib}(n) = \left( \frac{1 + \sqrt{5}}{2\sqrt{5}} \right) \left( \frac{1 + \sqrt{5}}{2} \right)^n + \left( \frac{\sqrt{5} - 1}{2\sqrt{5}} \right) \left( \frac{1 - \sqrt{5}}{2} \right)^n \]
Bunnies Revisited

What if we want to find the response exactly?

\[ y[n] = c_0(\phi_n^+) + c_1(\phi_n^-) \]

Two unknowns, and so need two equations.

\[ y[0] = 1 = c_0(\phi_0^+) + c_1(\phi_0^-) = c_0 + c_1 \]
\[ y[1] = 1 = c_0(\phi_1^+) + c_1(\phi_1^-) = c_0\phi_+ + c_1\phi_- \]

Solving:

\[ c_0 = \frac{1 + \sqrt{5}}{2\sqrt{5}} \]
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\[ fib(n) = \left( \frac{1 + \sqrt{5}}{2\sqrt{5}} \right) \left( \frac{1 + \sqrt{5}}{2} \right)^n + \left( \frac{\sqrt{5} - 1}{2\sqrt{5}} \right) \left( \frac{1 - \sqrt{5}}{2} \right)^n \]

\[ \sqrt{5} \approx 2.23606797749978969640917366873127623544061835961152572427 \]
>>> p0 = (1+5**0.5)/2
>>> p1 = (1-5**0.5)/2
>>> c0 = (1+5**0.5)/(2*5**0.5)
>>> c1 = (5**0.5-1)/(2*5**0.5)
>>> for n in range(20):
    print(c0*p0**n + c1*p1**n)

1.0
1.0
2.0
3.0
5.0
8.0
13.0
21.0
34.0
55.0
89.0
144.0
233.0
377.0
610.0
987.0
1597.0
2584.0
4181.0
6765.0